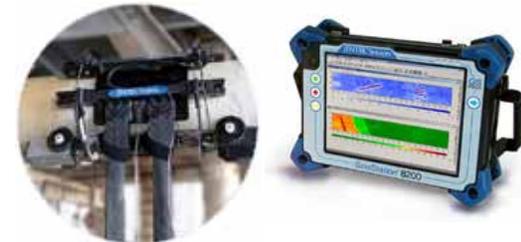


Field Demonstrations of MR-MWM-Array Solutions for Detection, Imaging and Sizing of Corrosion under Fireproofing (CUF) with Wire Mesh

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JENTEK® Sensors, Inc.



Problem Description

Internal and External Corrosion Imaging through Fireproofing

- **Requirements:**
 - Inspect large areas through fireproofing with and without wire mesh
 - Correct for variations in fireproofing thickness
 - Correct for variations in steel properties
 - Provide an image of the wall loss
 - Differentiate between external and internal corrosion
- **Applications include vessel skirts, LPG legs, structures**
- **Related applications include:**
 - Inspection through insulation with weather jacket for vessels and piping
 - In-line inspection for corrosion and longitudinal stress



Technology Summary / Overview

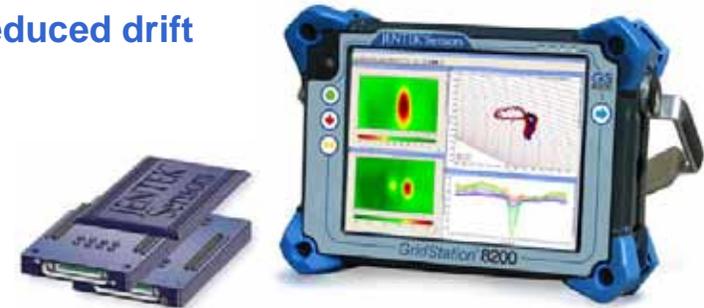
1. Sensors: MR-MWM[®]-Arrays

- **Paradigm shift** in sensor design (first priority is predictable response based on physics-based modeling)



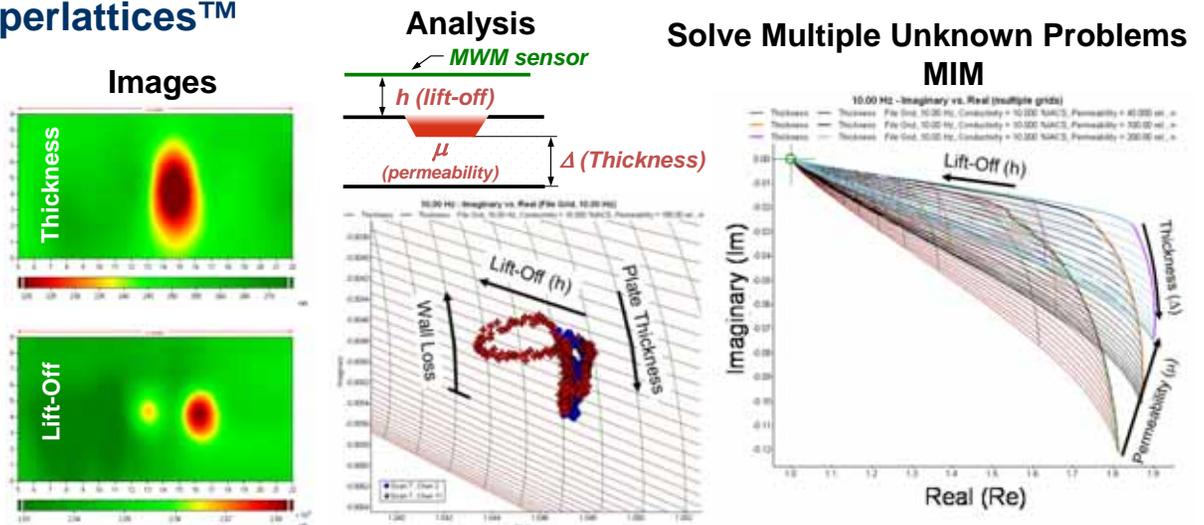
2. Next Generation 8200 α GridStation[®] Electronics

- 10x signal-to-noise improvement
- Very low frequencies (deep penetration)
- Crack detection through up to 0.5 inches of material
- Reduced drift



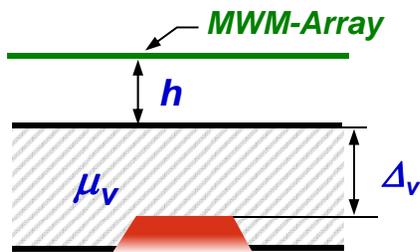
3. GridStation[®] Software using Hyperlattices[™]

- **Rapid, autonomous data analysis**
Performs multivariate inverse method (MIM) using precomputed databases
 - Defect Images
 - Performance Diagnostics
 - Noise Suppression



Consider Three Corrosion Imaging Problems

3-unknowns (CUF)



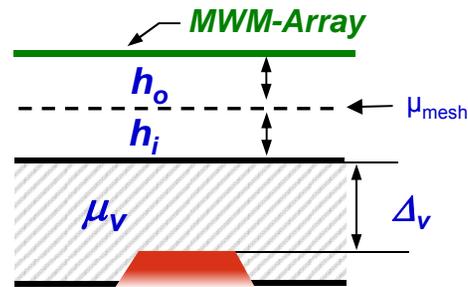
$$h, \Delta_v, \mu_v$$

h = insulation thickness + external metal loss

Δ_v = remaining vessel wall thickness

μ_v = vessel magnetic permeability

4-unknowns (CUF)



$$h, \Delta_v, \mu_v, \mu_{\text{mesh}}$$

h_o = distance between sensor & wire mesh = air gap + concrete thickness outside wire mesh

h_i = distance between wire mesh and external surface of vessel = concrete thickness inside wire mesh + external metal loss

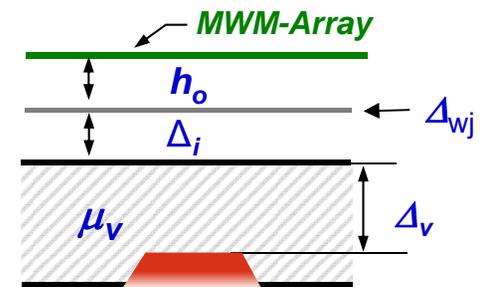
Δ_v = remaining vessel wall thickness

μ_v = vessel magnetic permeability

μ_{mesh} = effective magnetic permeability of the wire mesh for an assumed constant mesh thickness

NOTE: To simplify from 5 unknowns to 4 unknowns, h_i is assumed to be constant

5-unknowns (CUI)



$$h, \Delta_{\text{wj}}, \Delta_i, \Delta_v, \mu_v$$

h_o = distance between sensor & external surface of weather jacket

Δ_{wj} = weather jacket thickness

Δ_i = insulation thickness + external metal loss

Δ_v = remaining vessel wall thickness

μ_v = vessel magnetic permeability

Demonstrations at Two Saudi Aramco Facilities

- Site teams included: Saudi Aramco, Al-Rushaid and JENTEK personnel
- Prototype scanner functioned well, but was too heavy. Modifications will be made to improve ease of use.
- Scanning of large areas was accomplished in multiple vertical passes, with automatic scanning in the vertical direction, and manual shifting of the scanner around the vessel.



How many Frequencies are Needed to Solve for 3-Unknowns?

2-unknowns (CUF)

1 Frequency

h and Δ_V

Linear equations example

$$h + \Delta_V = 3 \text{ in.}$$

$$\Delta_V = 1 \text{ in.}$$

Solve: $h = 2 \text{ in.}$

Nonlinear equations example:

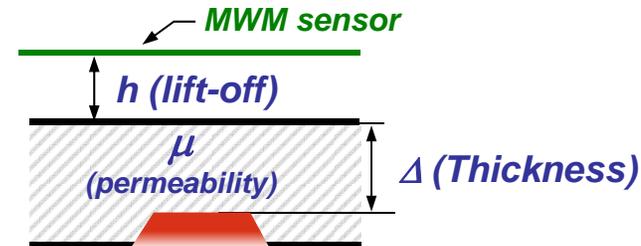
$$\text{Function 1 (} h \text{ and } \Delta_V) = S1 = \text{Re}(V/I)$$

$$\text{Function 2 (} h \text{ and } \Delta_V) = S2 = \text{Im}(V/I)$$

Must solve using an alternative method.

3-unknowns (CUF)

2 Frequencies



Function 1 (h, Δ_V, μ_V) = $S1 = \text{Re}(V/I)$ at $f1$

Function 2 (h, Δ_V, μ_V) = $S2 = \text{Im}(V/I)$ at $f1$

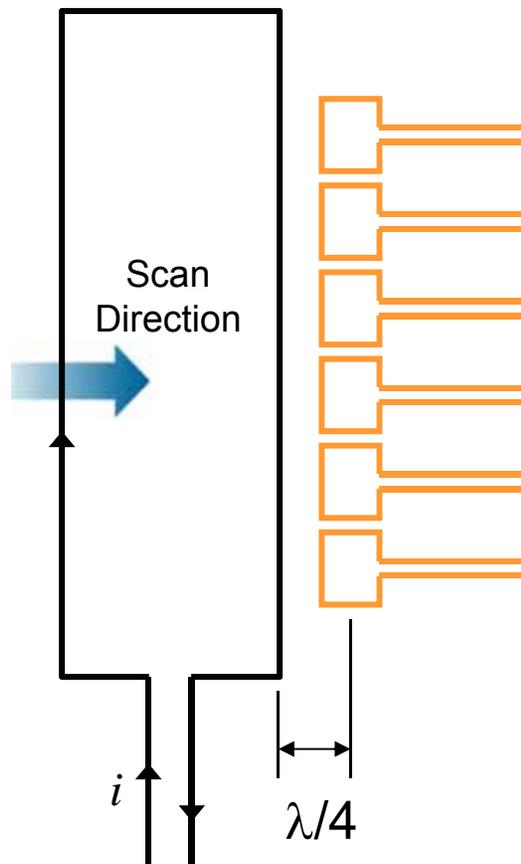
Function 3 (h, Δ_V, μ_V) = $S3$ need 2nd freq.

For Low Frequency Eddy Current Sensing

Each frequency provides two equations.

Thus, to solve a three unknown problem, two frequencies are needed. To solve a two unknown problem, only one frequency is needed. For 5 unknowns, three frequencies are needed.

A Quick Introduction to MWM-Array Eddy Current Sensing



1. A current is applied to a single large drive conductor
2. This time varying current is applied at a frequency, such as 5Hz (5 cycles/second)
3. This time varying current produces a magnetic field
4. The electronics measures a voltage at each sensing element at the same time for up to three frequencies at the same time
5. For each frequency a magnitude (V/I) is measured and a phase which is the time delay of the voltage relative to the current is measured
6. The Real part of the impedance is the Magnitude $\times \cos(\text{phase})$; the Imaginary part of the impedance is the Magnitude $\times \sin(\text{phase})$

Flat Plate Demonstration of 3-Unknown Method

For External and Internal Corrosion

Sensor

- 18-channel sensor
- Motorized scanning vehicle
- External and internal wall loss imaging

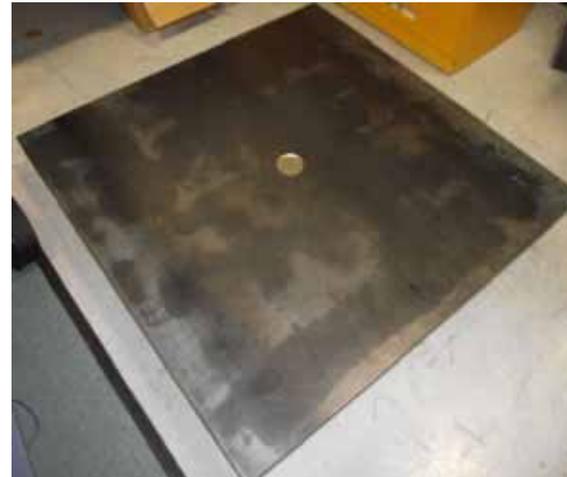
Flat Plate

Dimensions: 4 ft. x 4 ft.
Thickness: 0.25 in.

Flaw

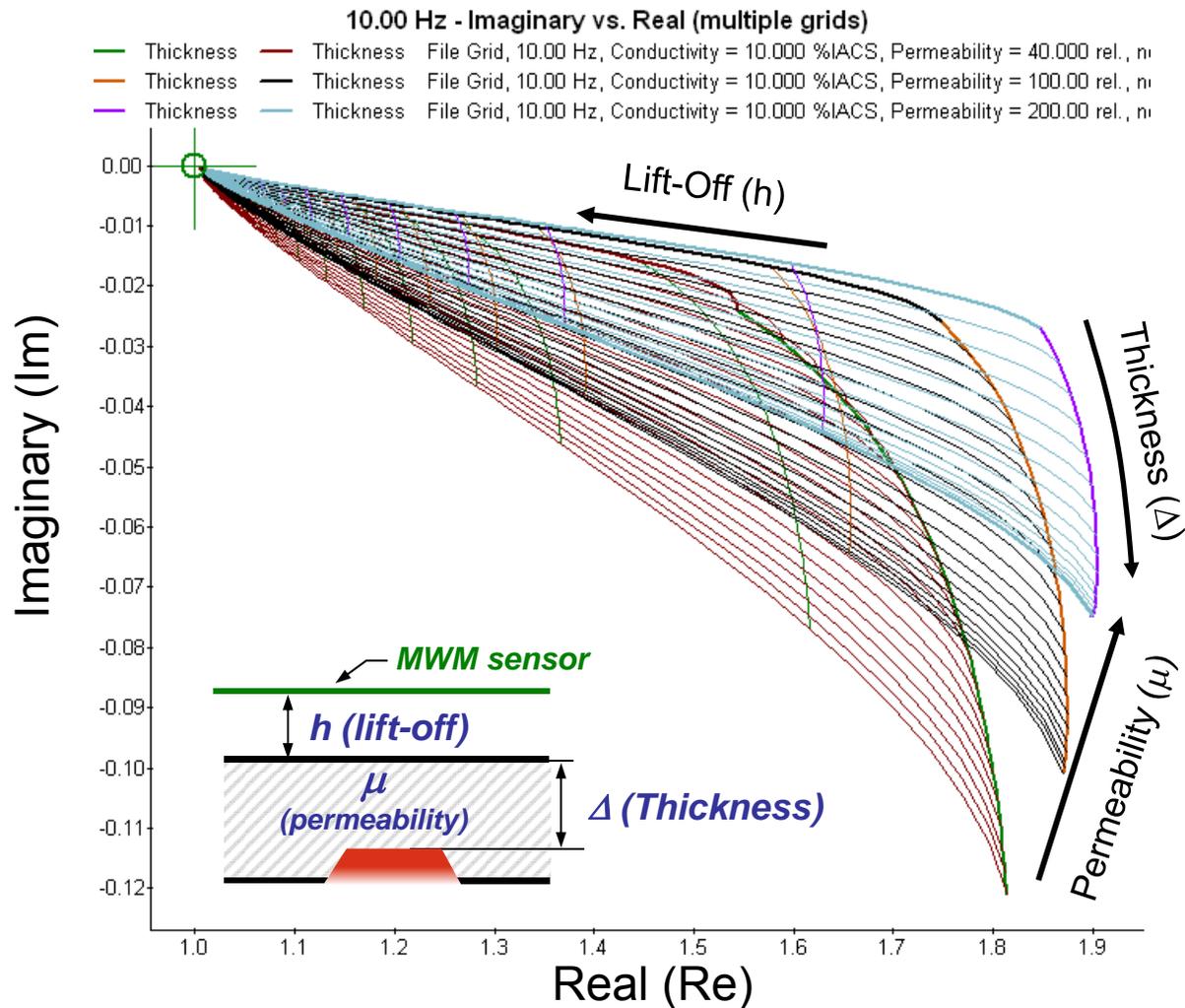
Diameter: 2.25 in.
Depth: 0.150 in.

MR-MWM-Array
(Curved or Flat surfaces)



3-Unknown Lattices

- GridStation Lattices for MR-MWM-Array **wall loss imaging**
- Used for **external and internal** wall loss imaging



$|Z| = \text{Magnitude}$

$\theta = \text{Phase}$

$$|Z| = \sqrt{\text{Re}^2 + \text{Im}^2}$$

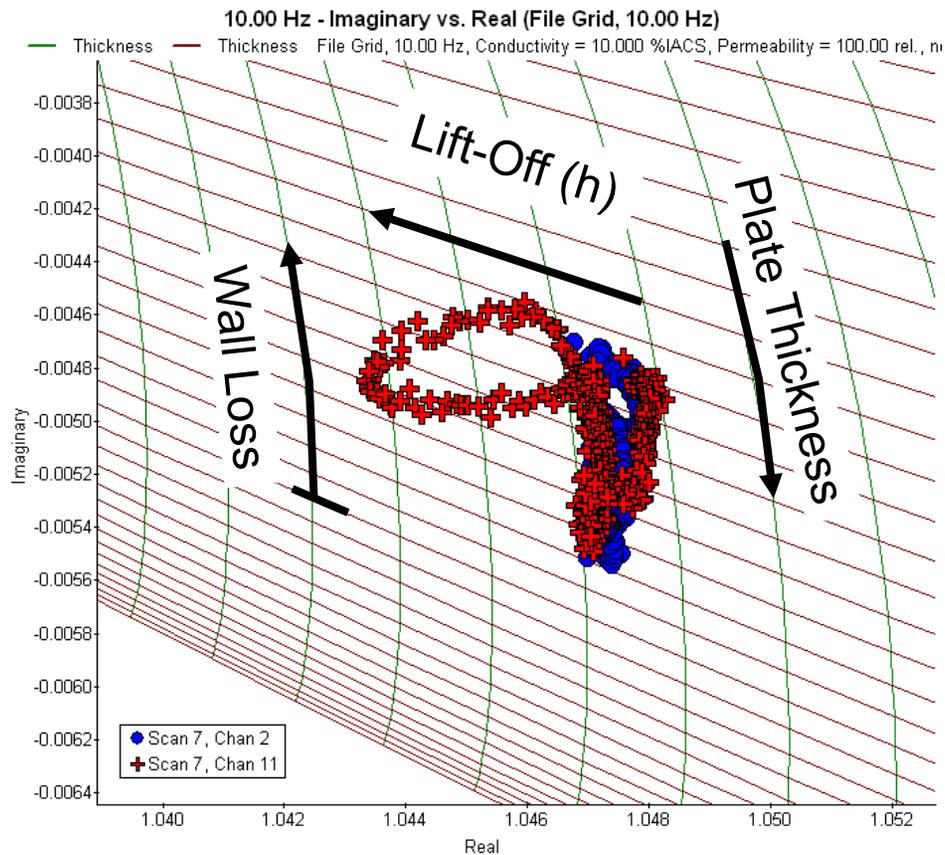
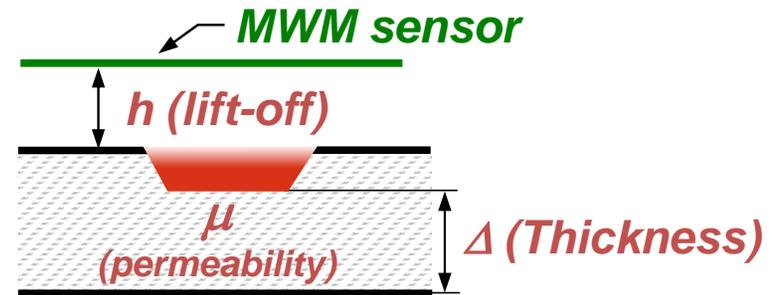
$$\theta = \arctan(\text{Im}/\text{Re})$$

$$\text{Re} = |Z|\sin(\theta)$$

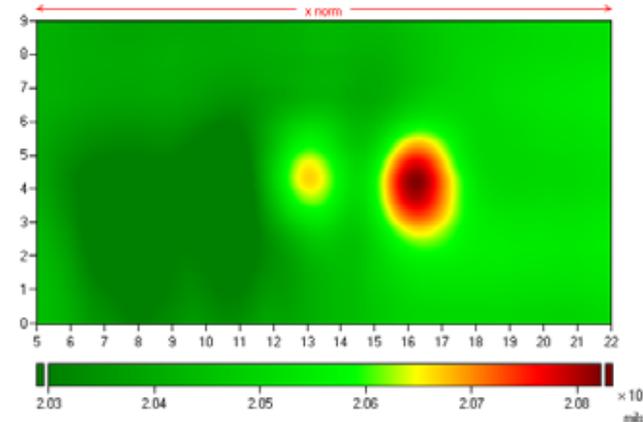
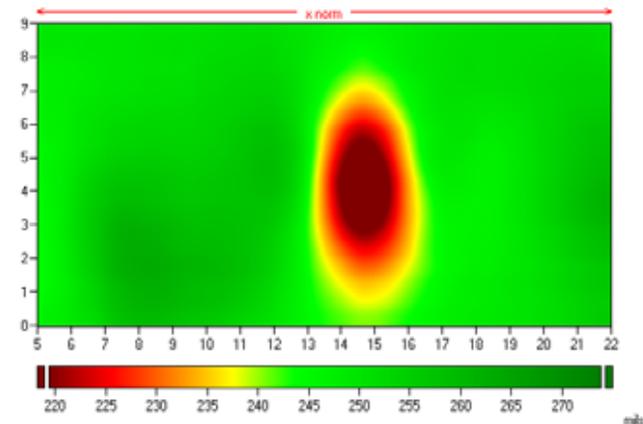
$$\text{Im} = |Z|\cos(\theta)$$

Independent Plate Thickness and Lift-off Imaging

- Channel over defect shows defect signature as thickness reduction and lift-off increase

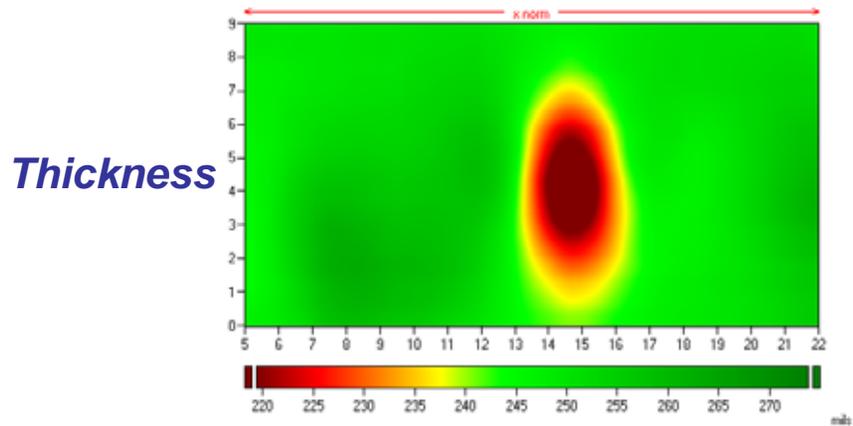


JENTEK GridStation Visualization

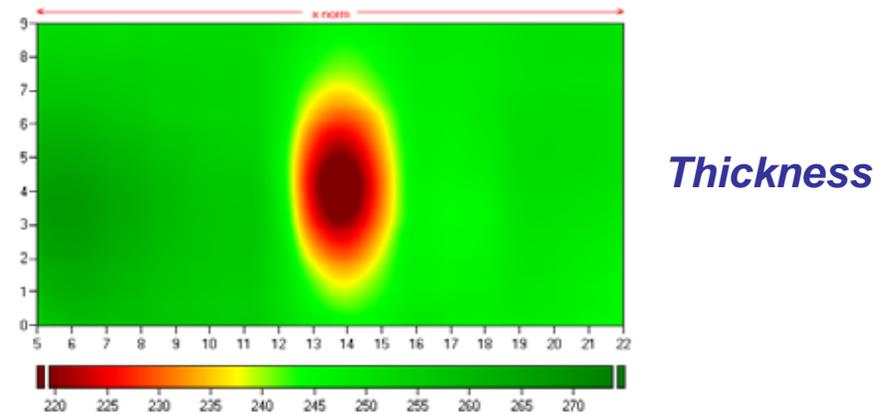


Discrimination Between External and Internal Wall Loss

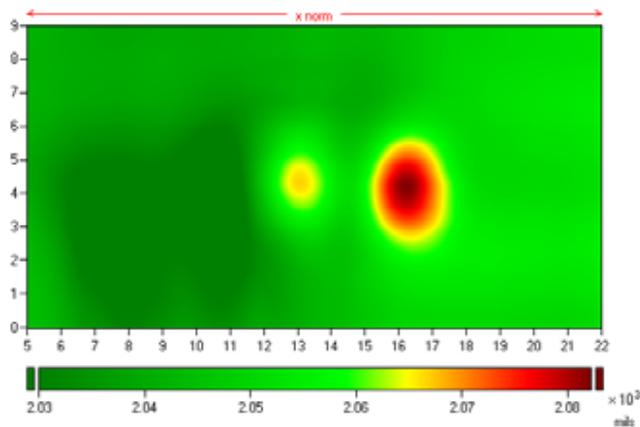
External Wall Loss



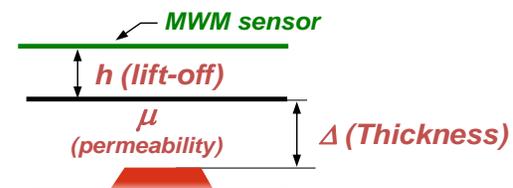
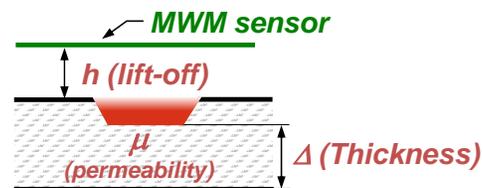
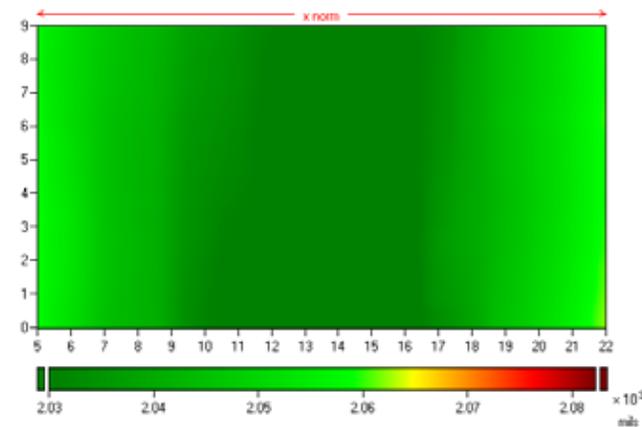
Internal Wall Loss



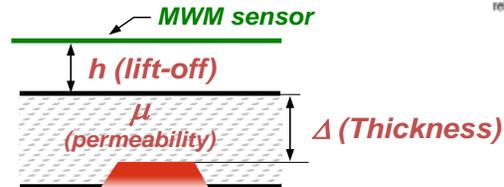
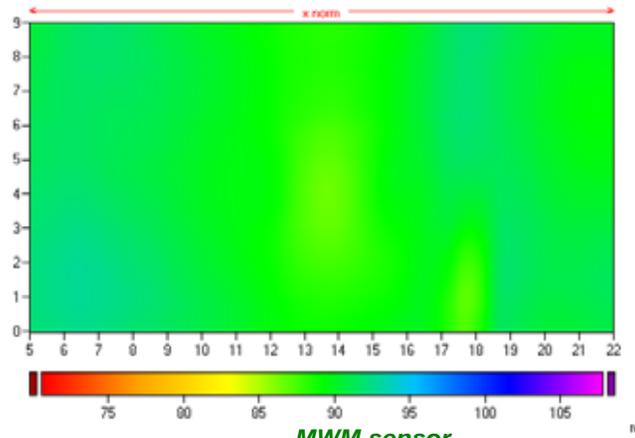
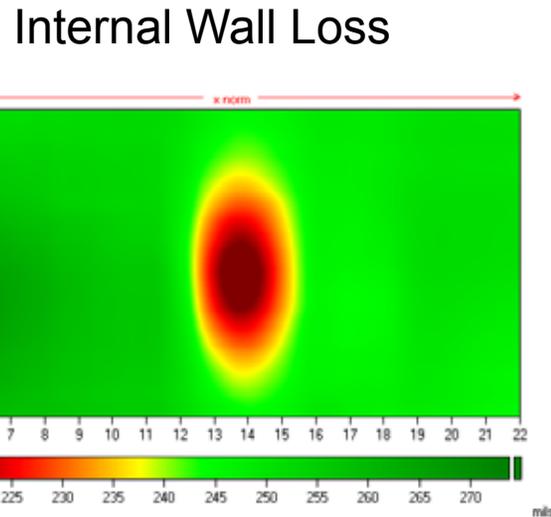
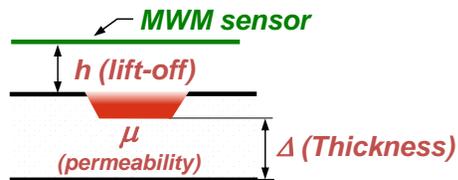
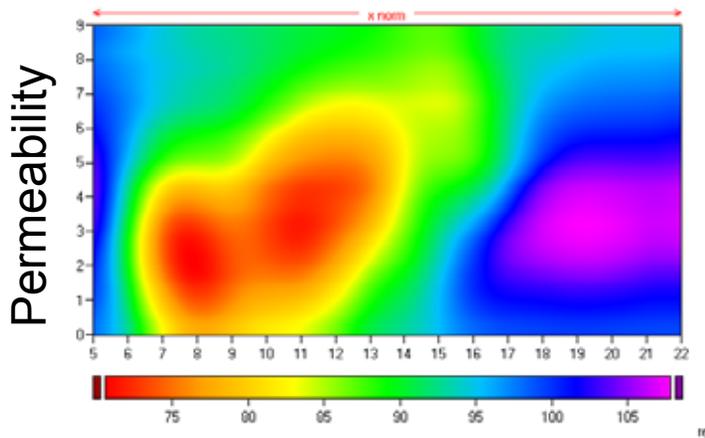
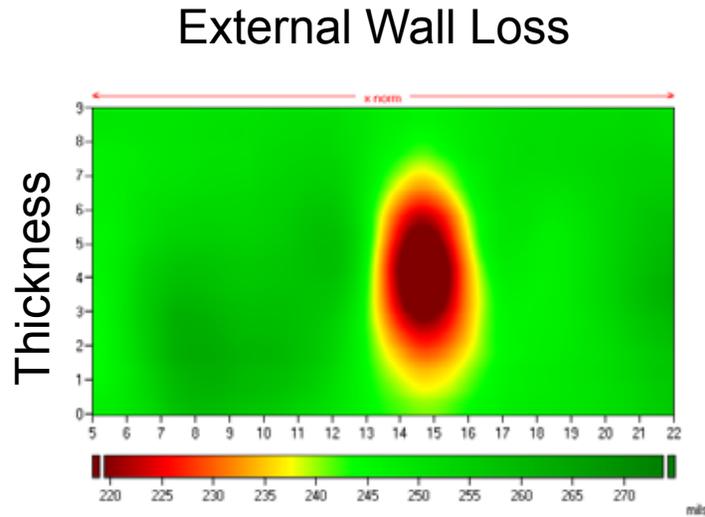
Lift-Off



Lift-Off



Independent Wall Thickness and Permeability (Longitudinal Stress) Imaging



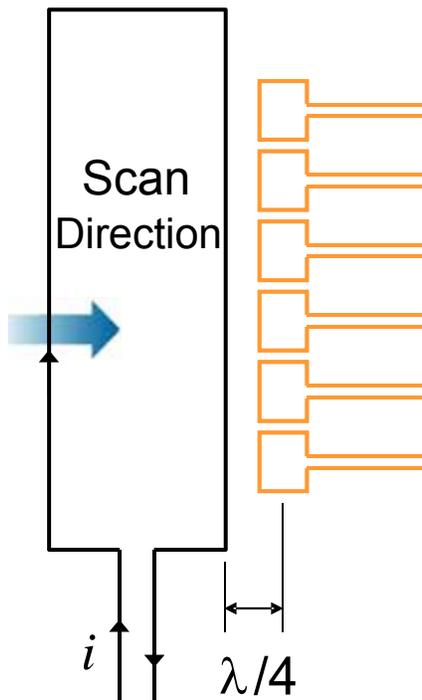
Thickness

Magnetic Permeability

- Need to add correction for sensor construct effects
- Longitudinal permeability is related to stress

MWM-Array Sensor Selection

- Decay rate determined by skin depth at high frequency and sensor dimensions at low frequency
- Large dimensions needed for thick coatings/insulation
- Low frequencies needed to penetrate through steel pipe wall

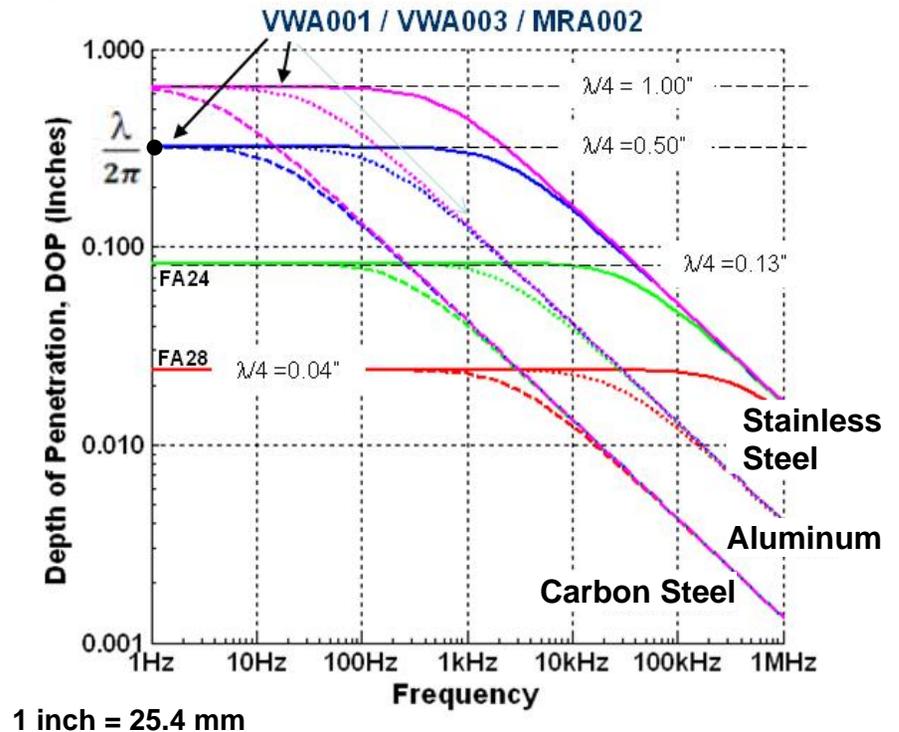


$$\text{Depth of Penetration} = 1/\text{Re}(\Gamma_n)$$

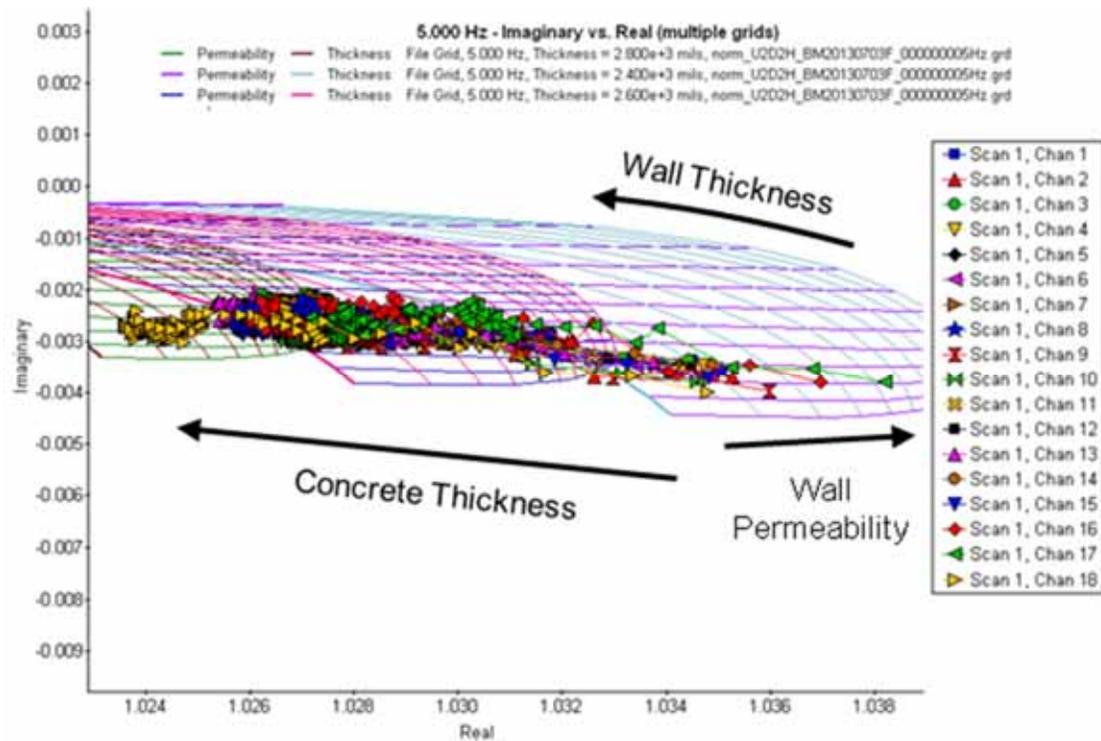
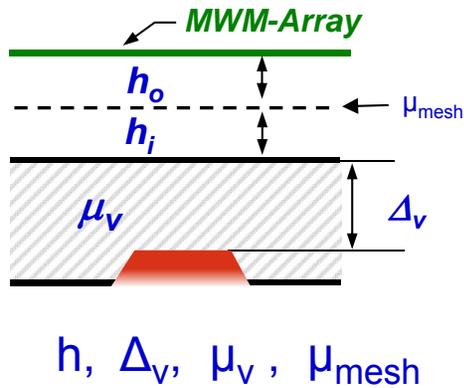
$$\text{Low Frequency Limit} = \frac{\lambda}{2\pi}$$

$$\Gamma_n = \sqrt{(2\pi n / \lambda)^2 + j2 / \delta^2}$$

$$\text{Skin depth: } \delta = \sqrt{\frac{1}{\pi f \mu \sigma}}$$



Corrosion Under Fireproofing (CUF) with Wire Mesh

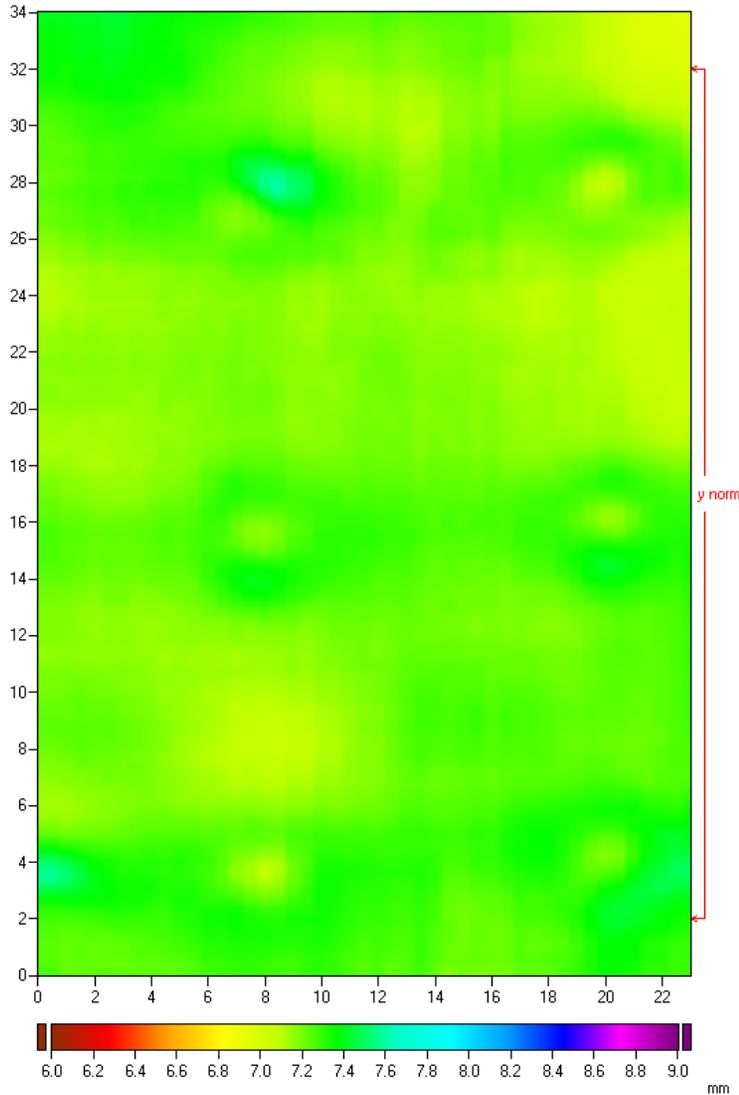


Vessel Scanner

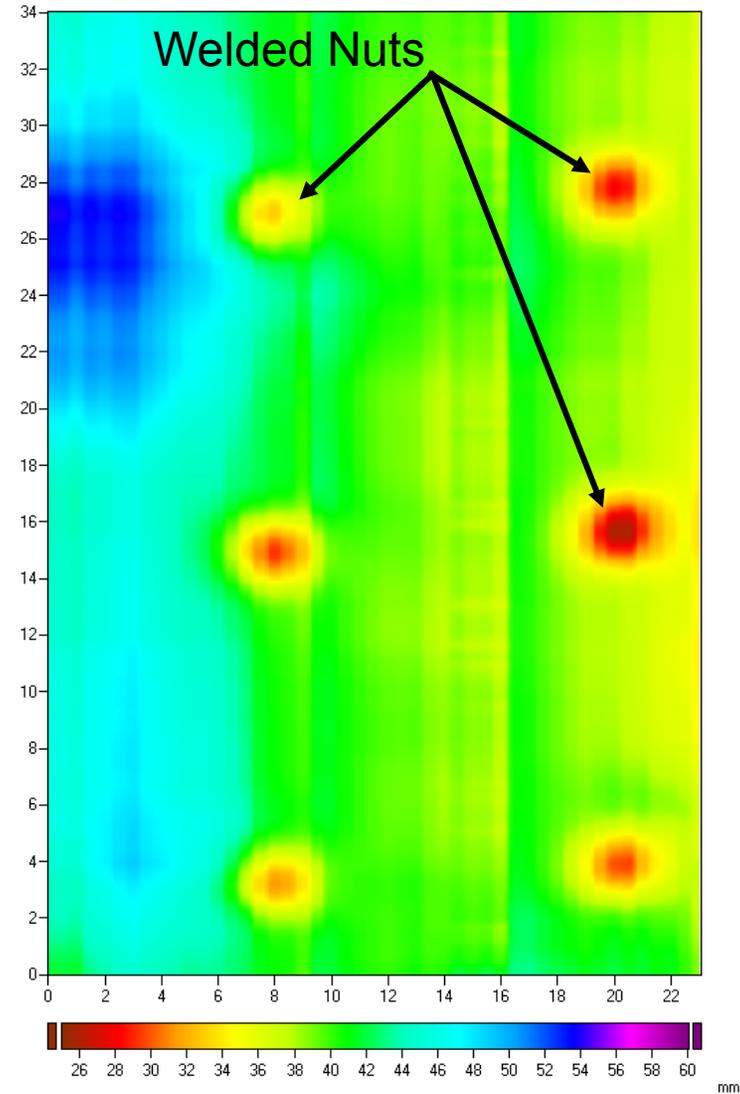


Wall Thickness and Concrete Thickness

Wall Thickness

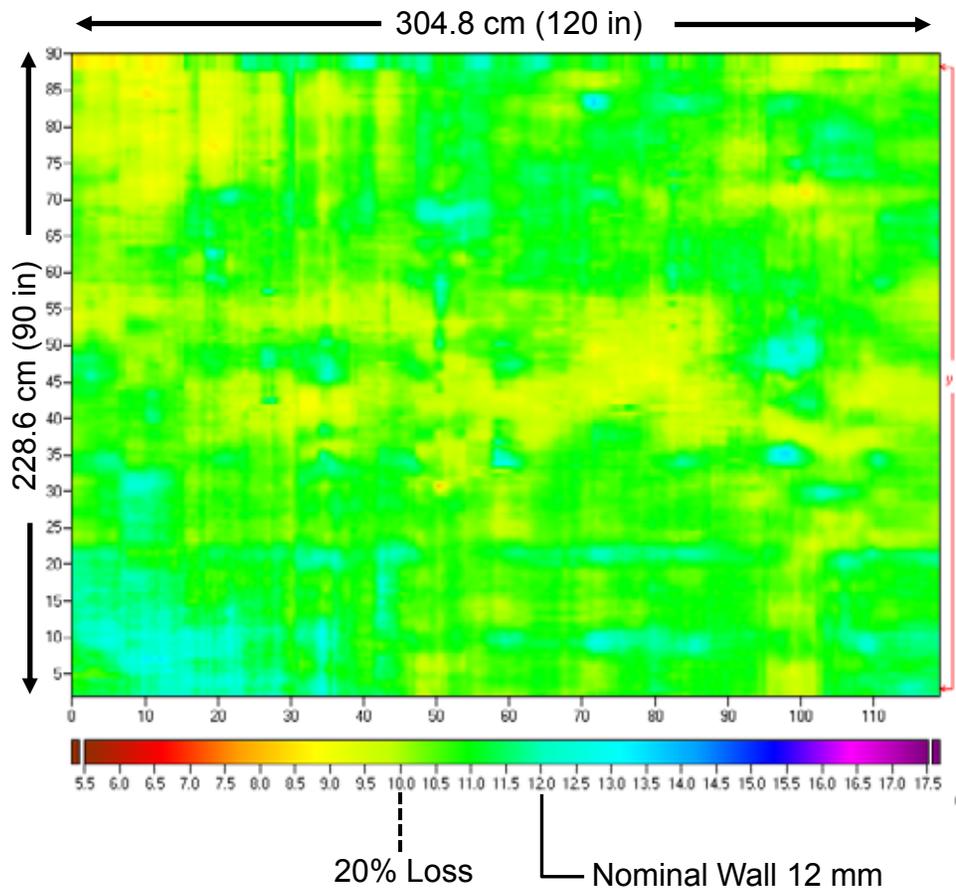


Concrete Thickness

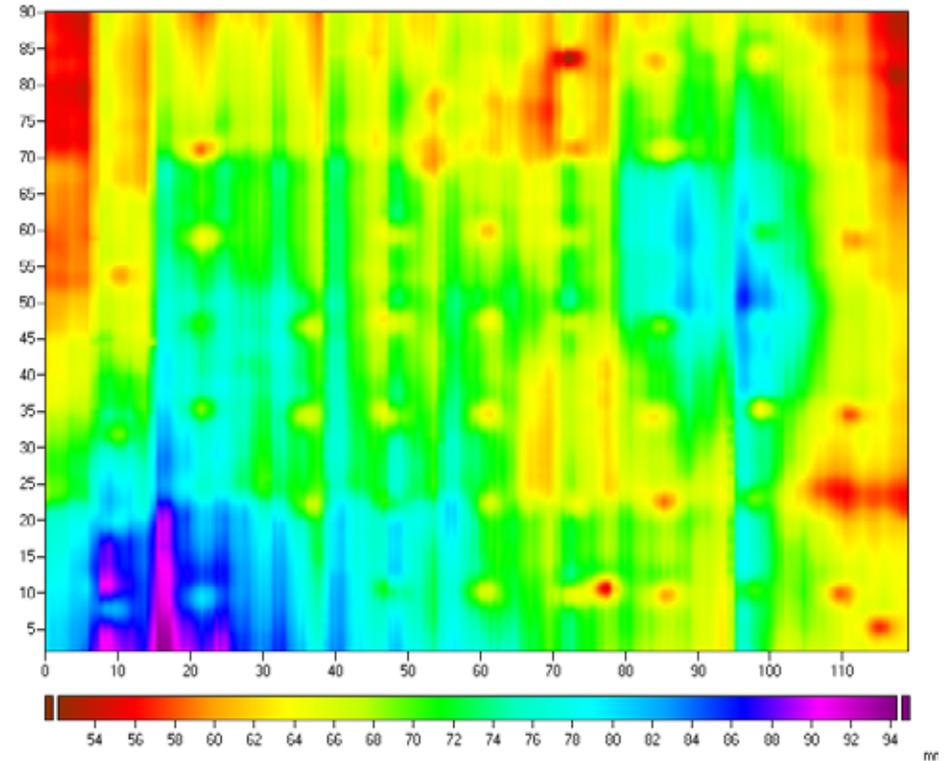


Wall Thickness and Concrete Thickness

Wall Thickness

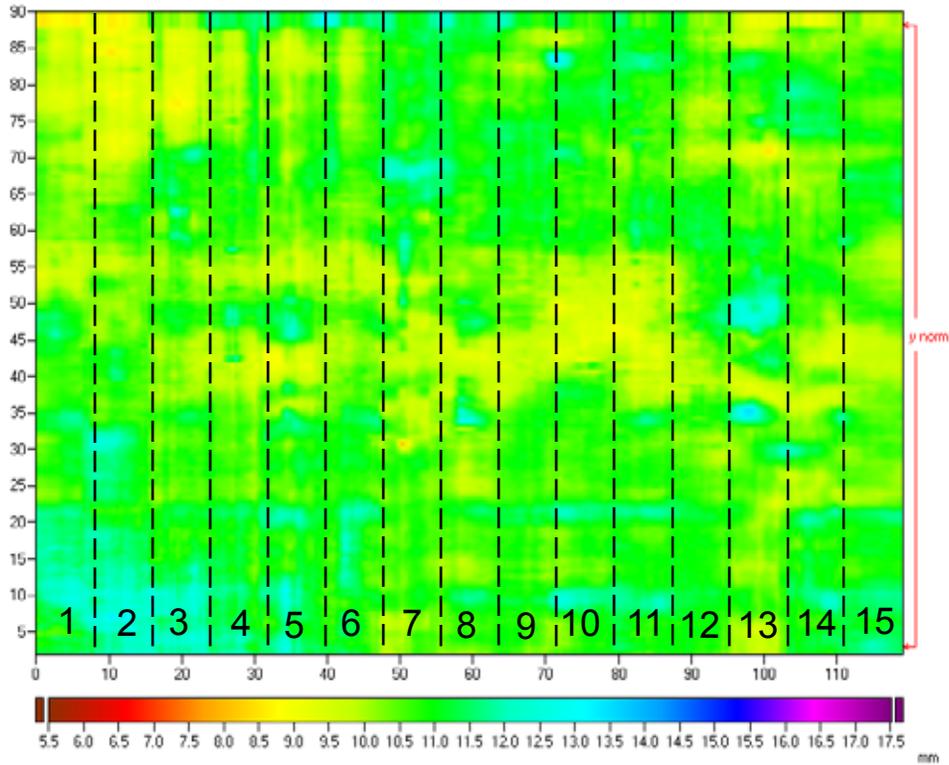


Concrete Thickness

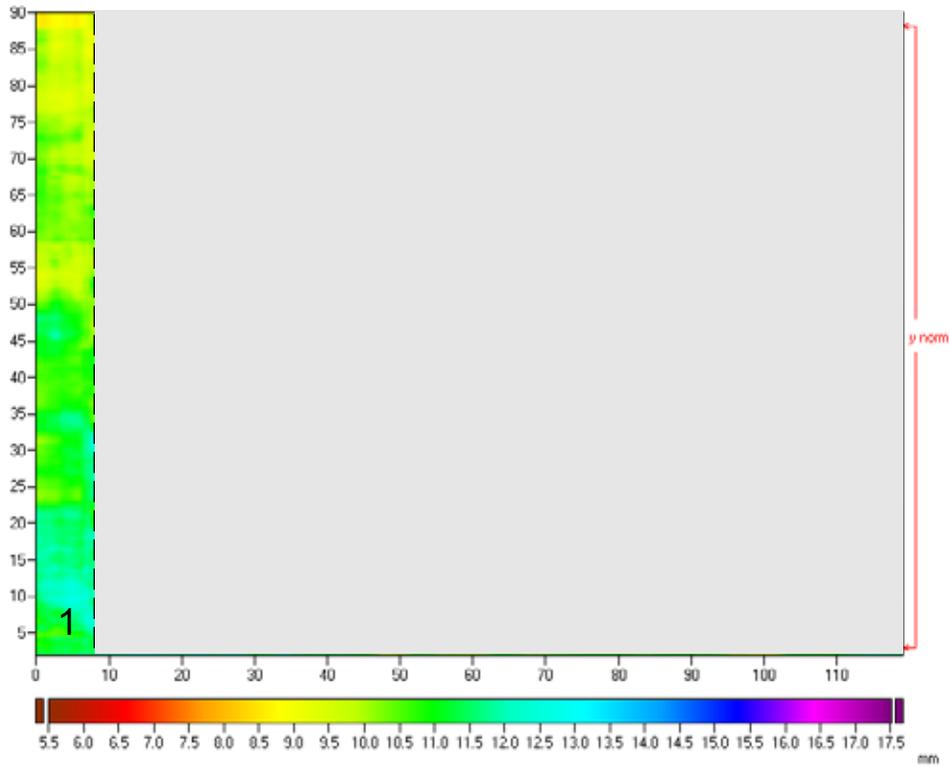


Note that typical steel plate varies by $\pm 10-15\%$ without corrosion

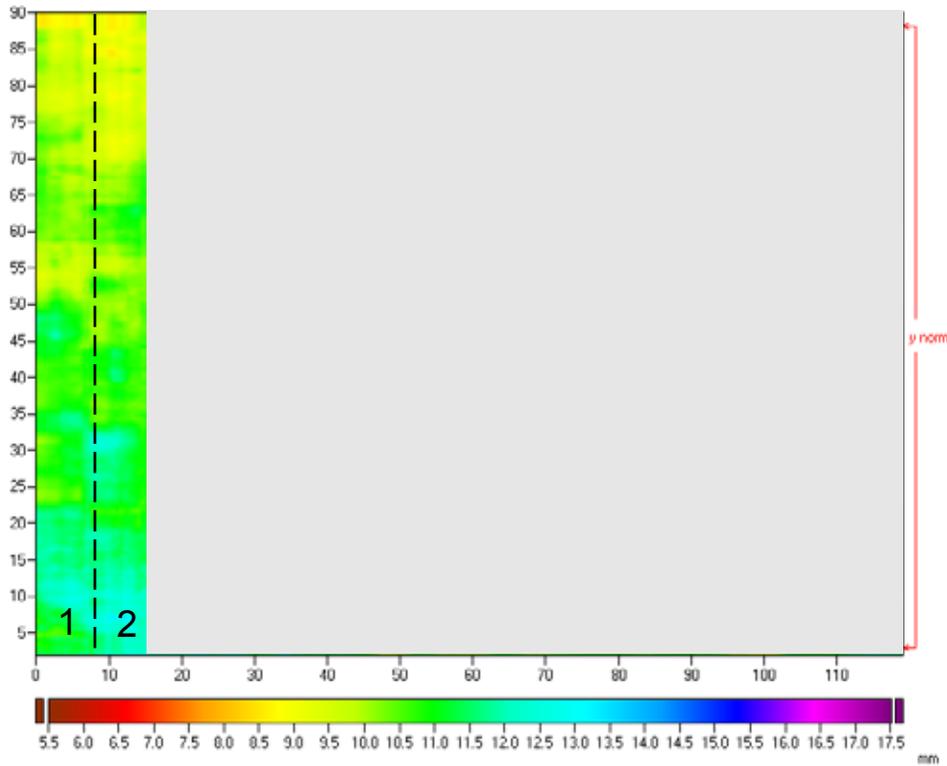
Building Thickness Image from Multiple Scans



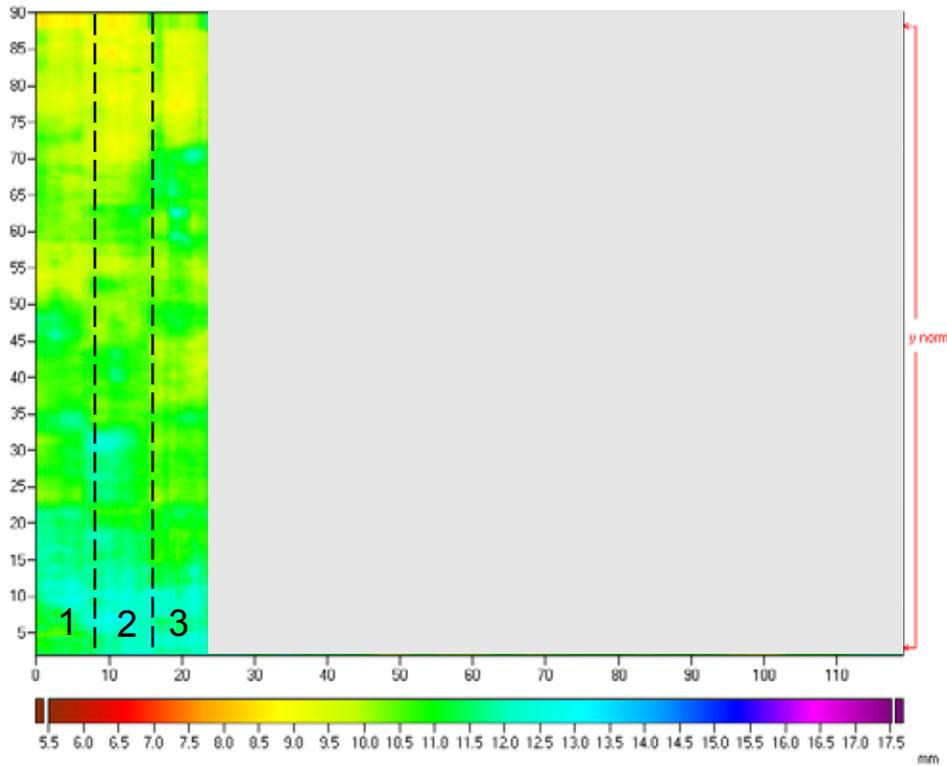
Building Thickness Image from Multiple Scans



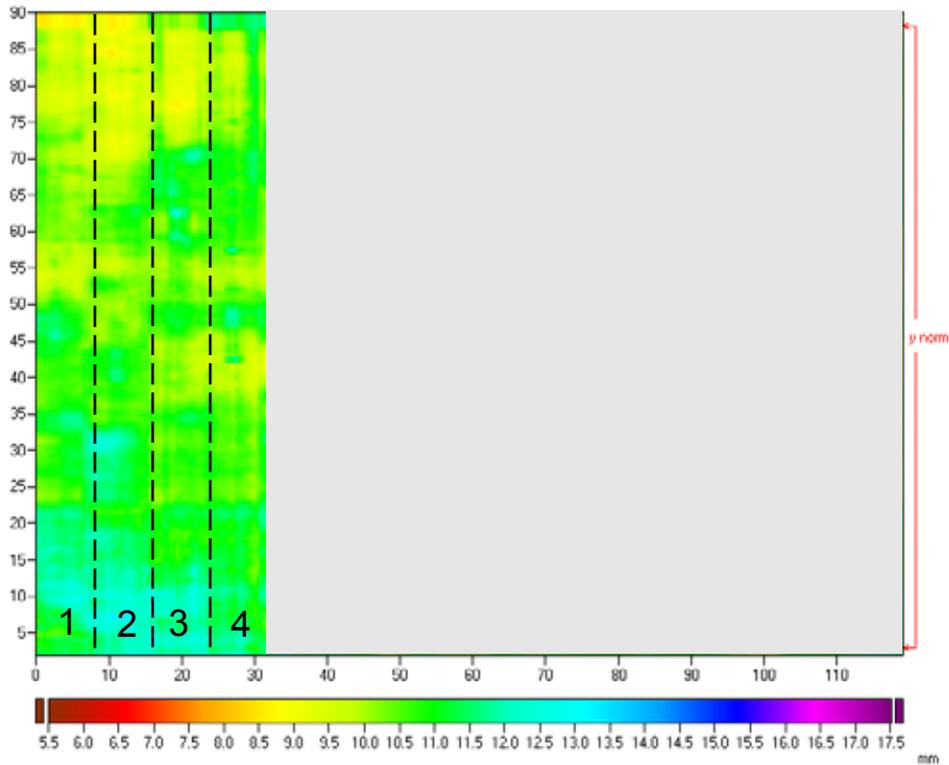
Building Thickness Image from Multiple Scans



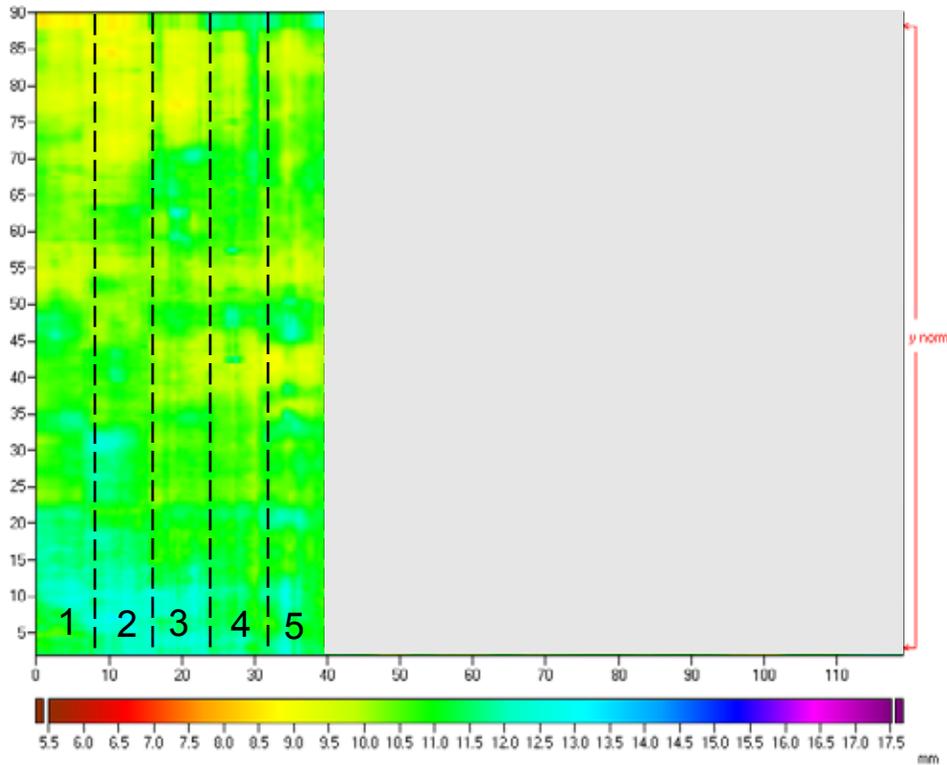
Building Thickness Image from Multiple Scans



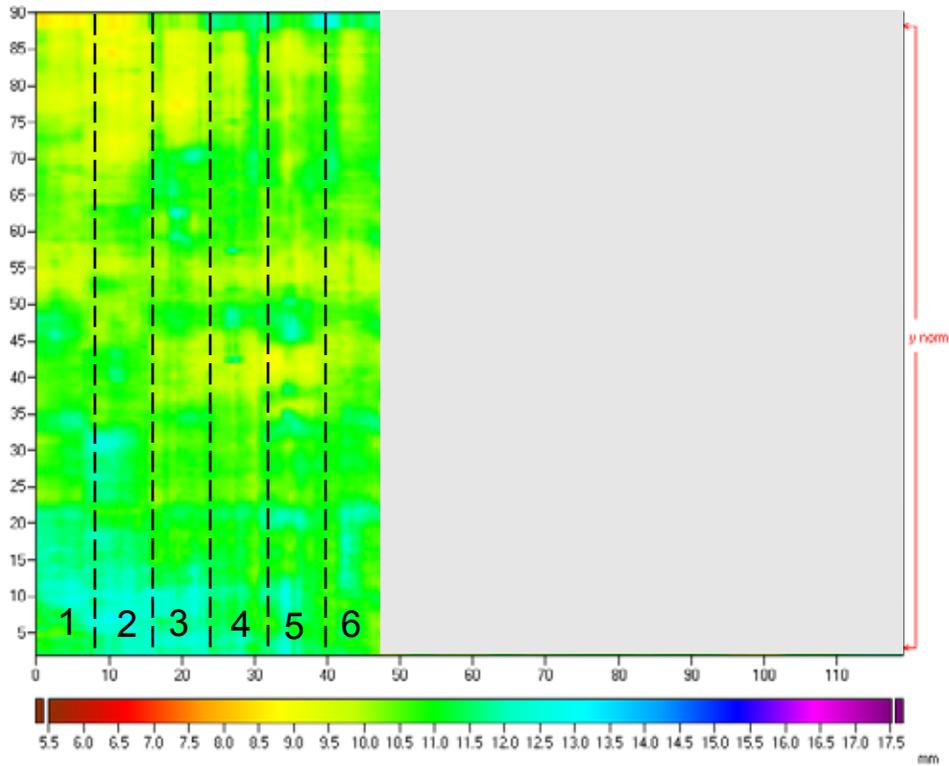
Building Thickness Image from Multiple Scans



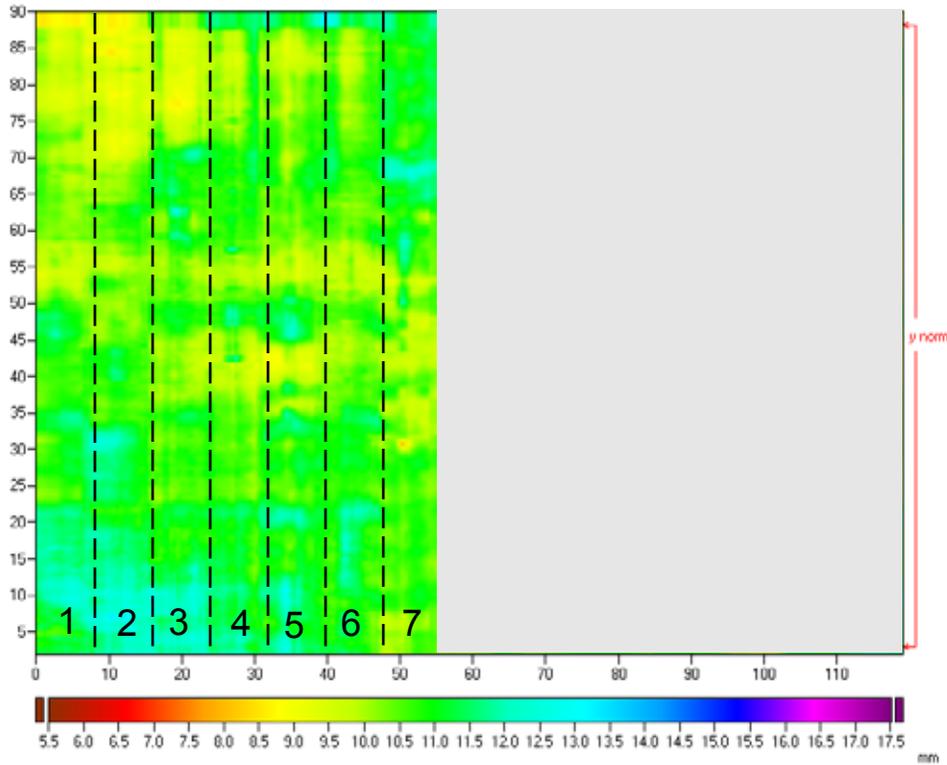
Building Thickness Image from Multiple Scans



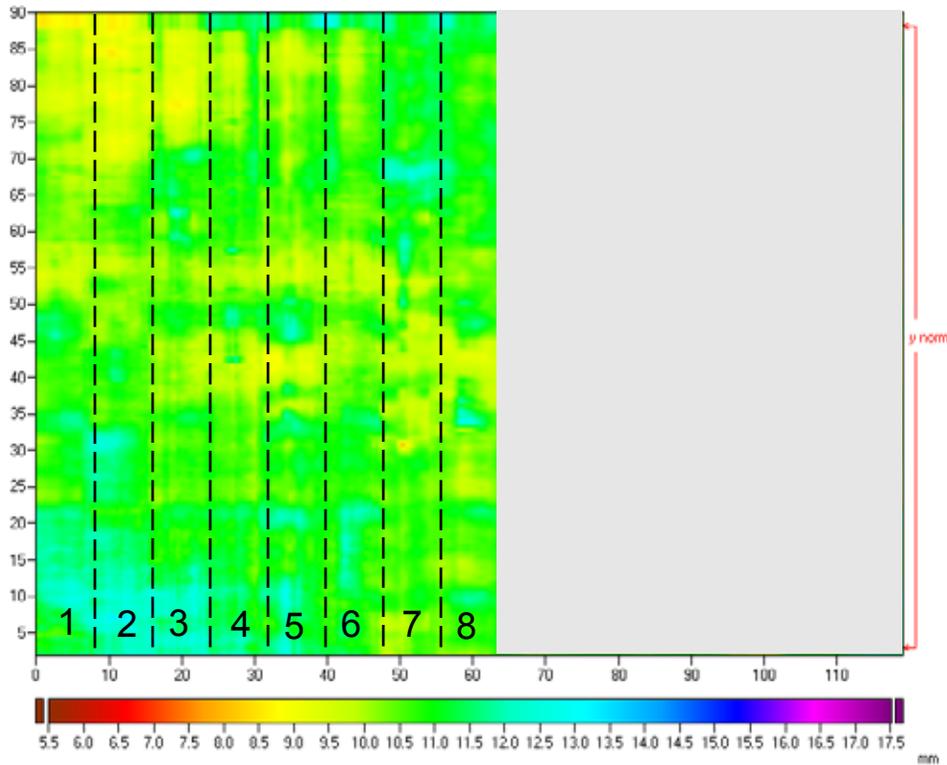
Building Thickness Image from Multiple Scans



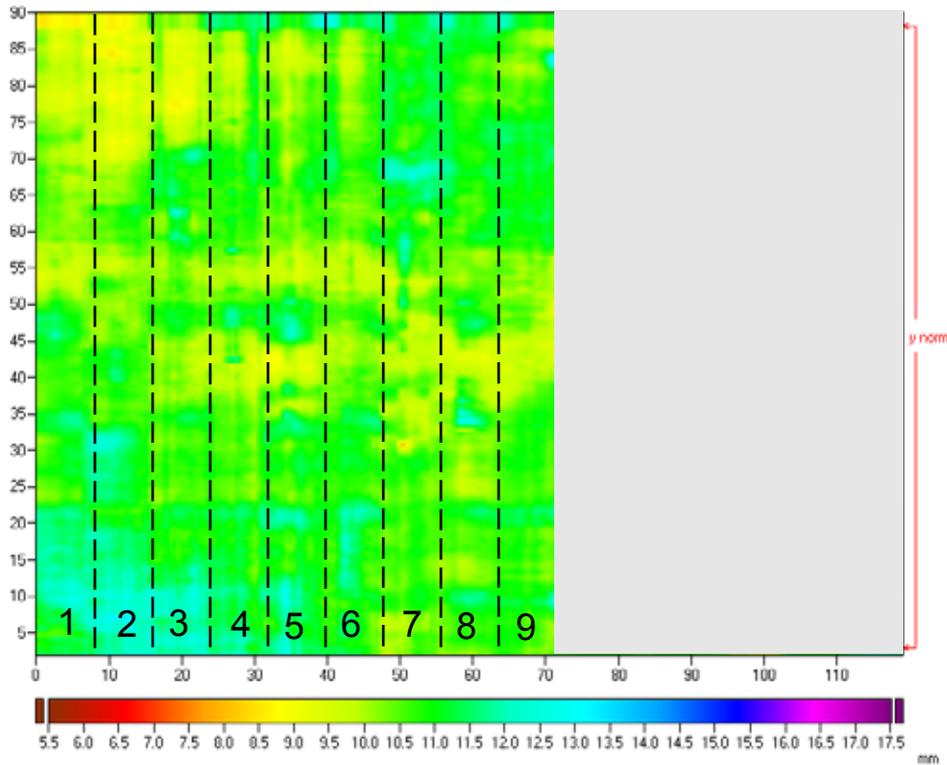
Building Thickness Image from Multiple Scans



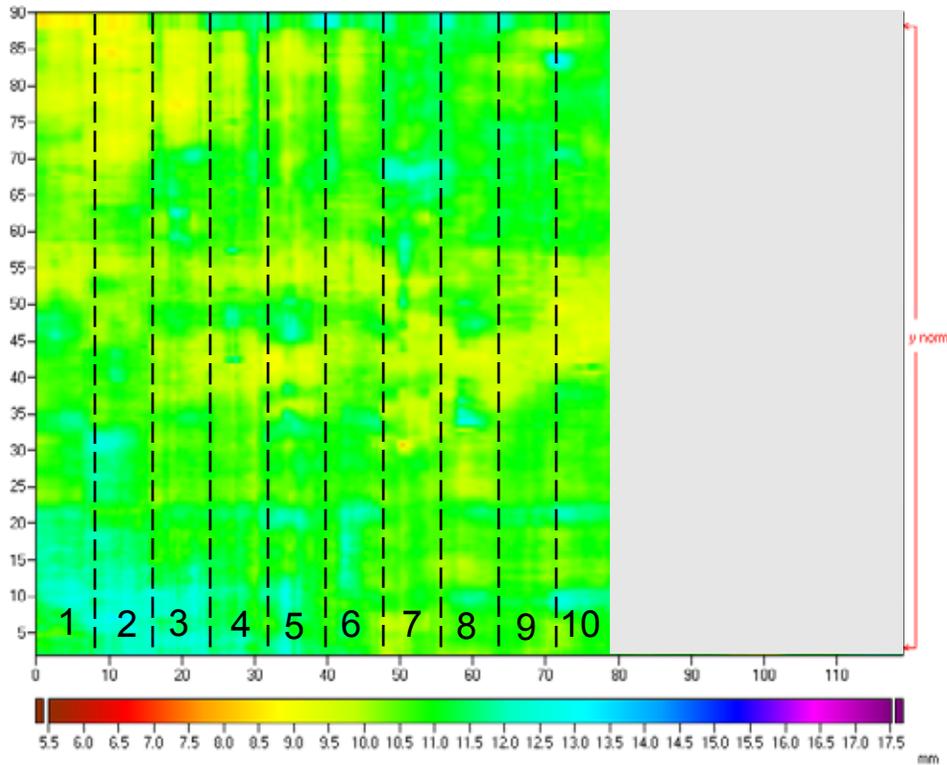
Building Thickness Image from Multiple Scans



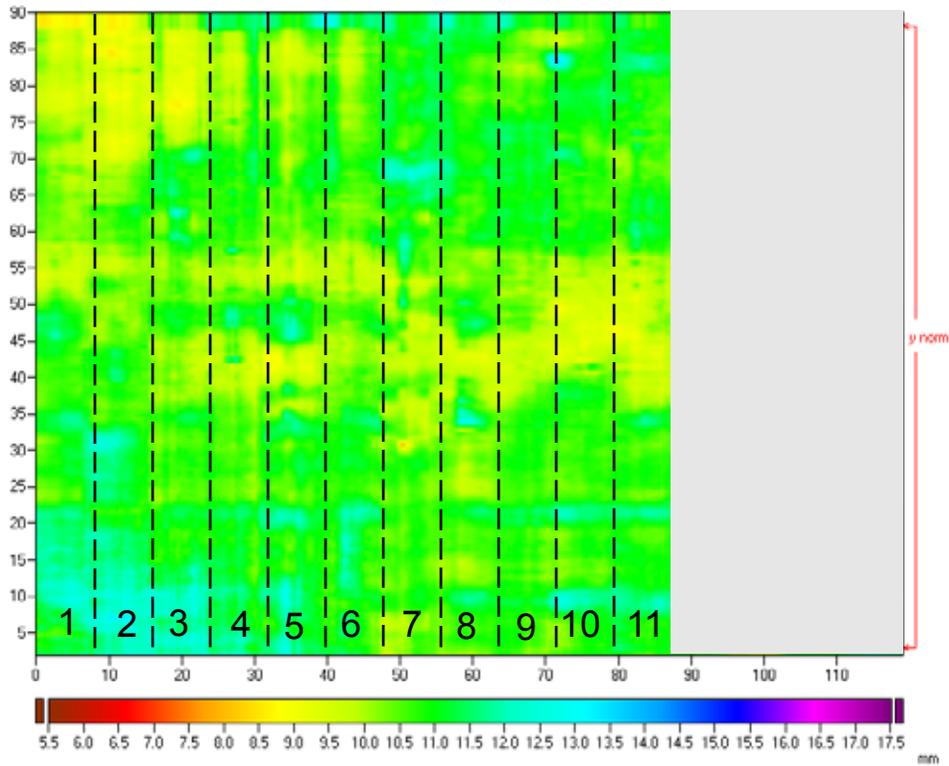
Building Thickness Image from Multiple Scans



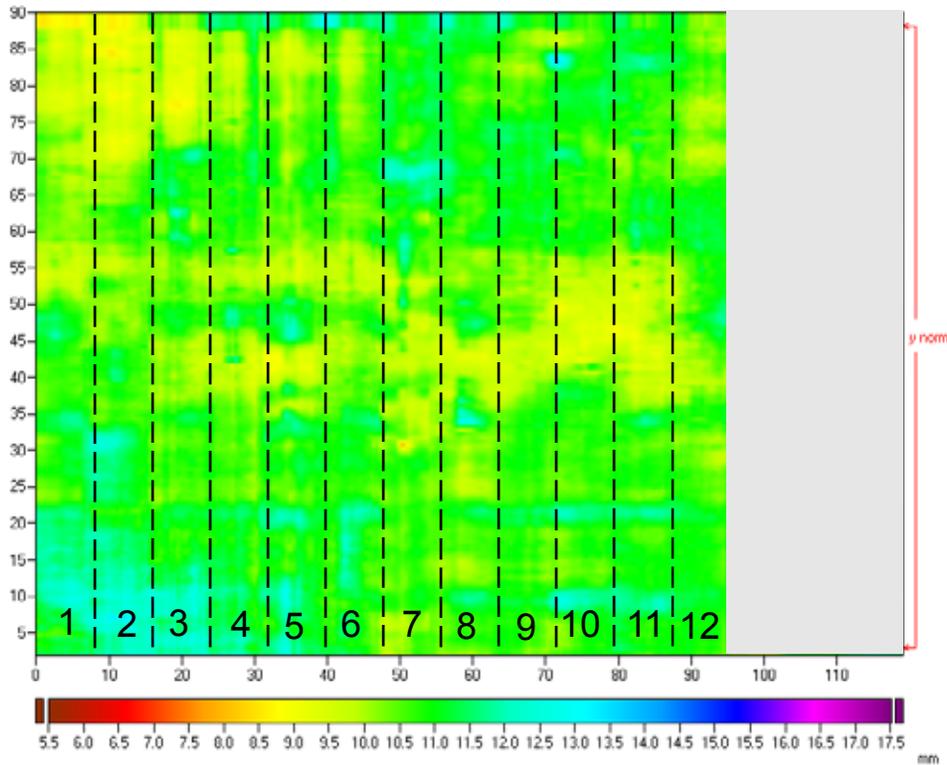
Building Thickness Image from Multiple Scans



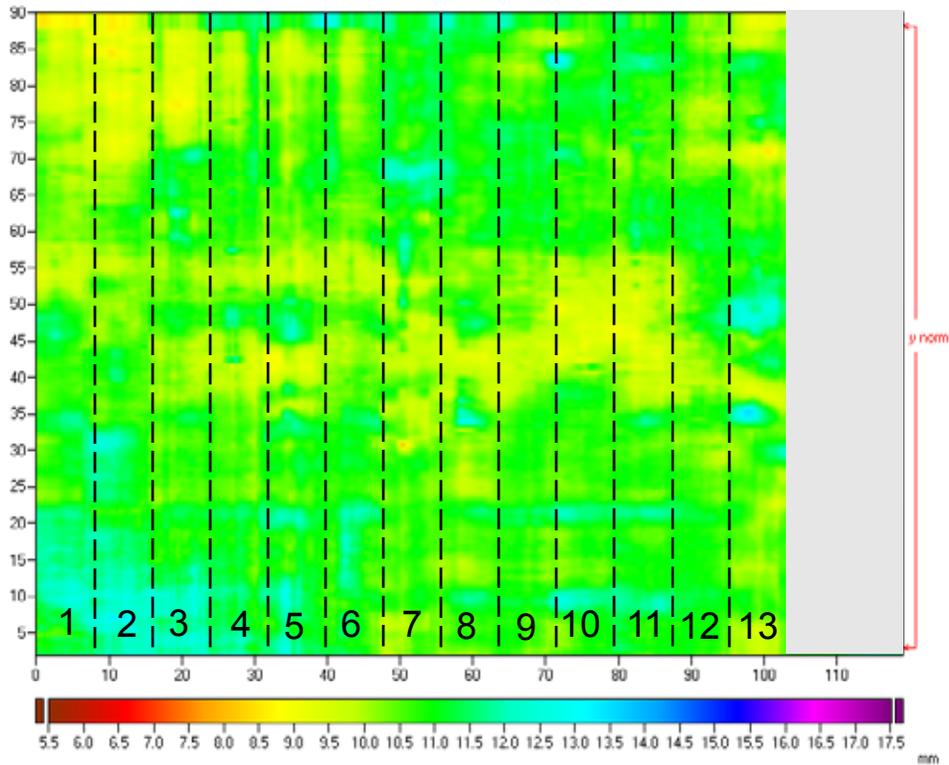
Building Thickness Image from Multiple Scans



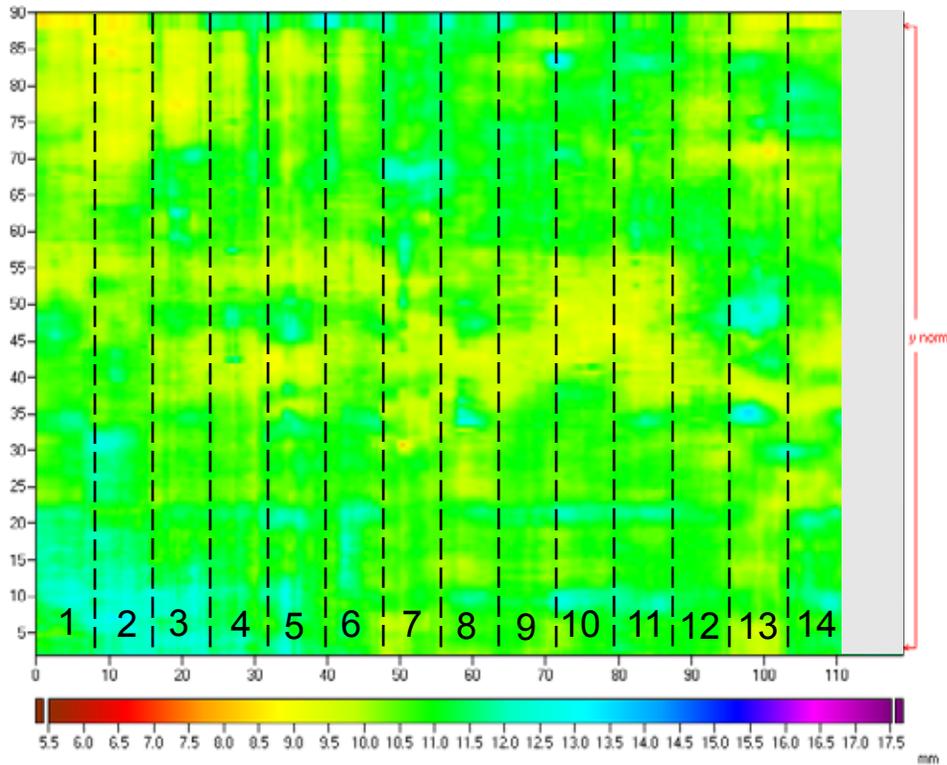
Building Thickness Image from Multiple Scans



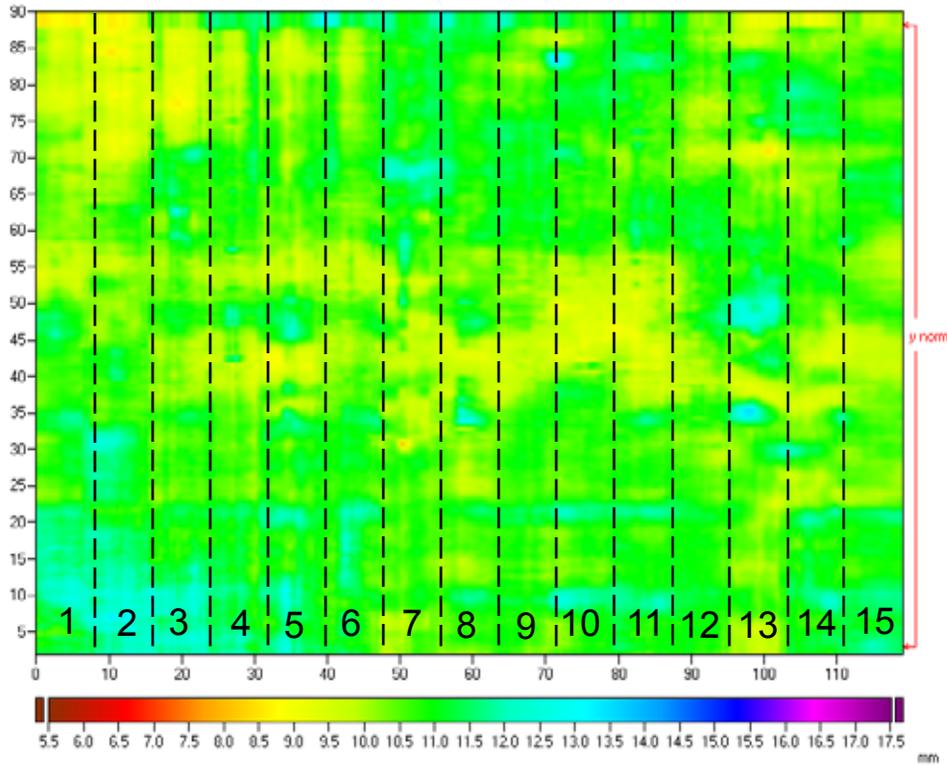
Building Thickness Image from Multiple Scans



Building Thickness Image from Multiple Scans

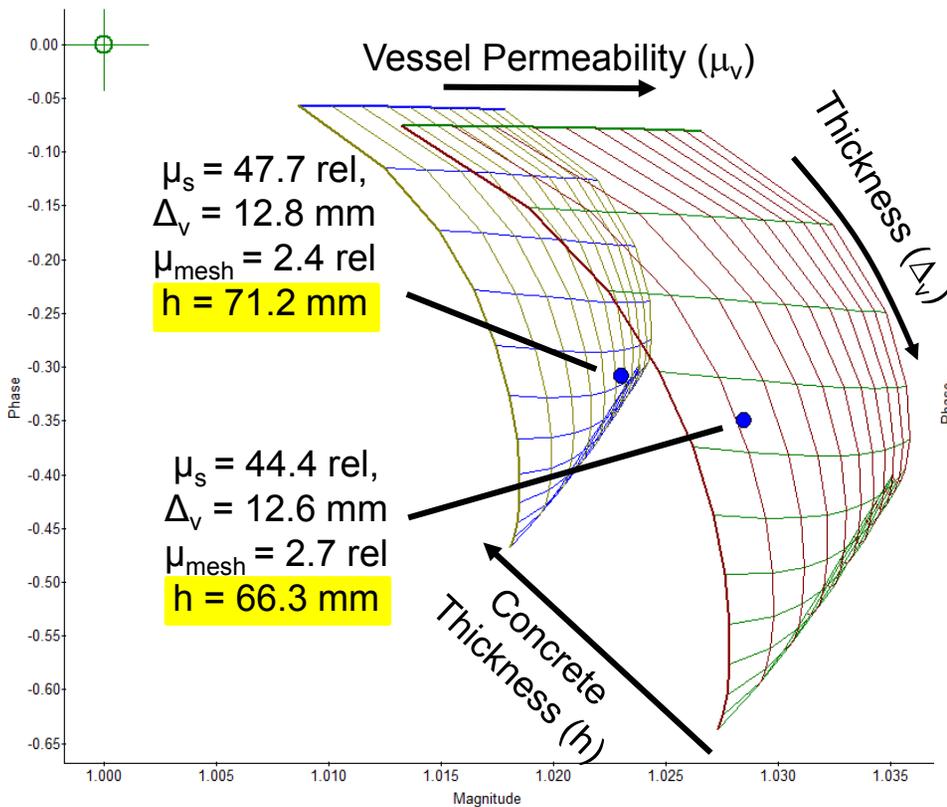


Building Thickness Image from Multiple Scans

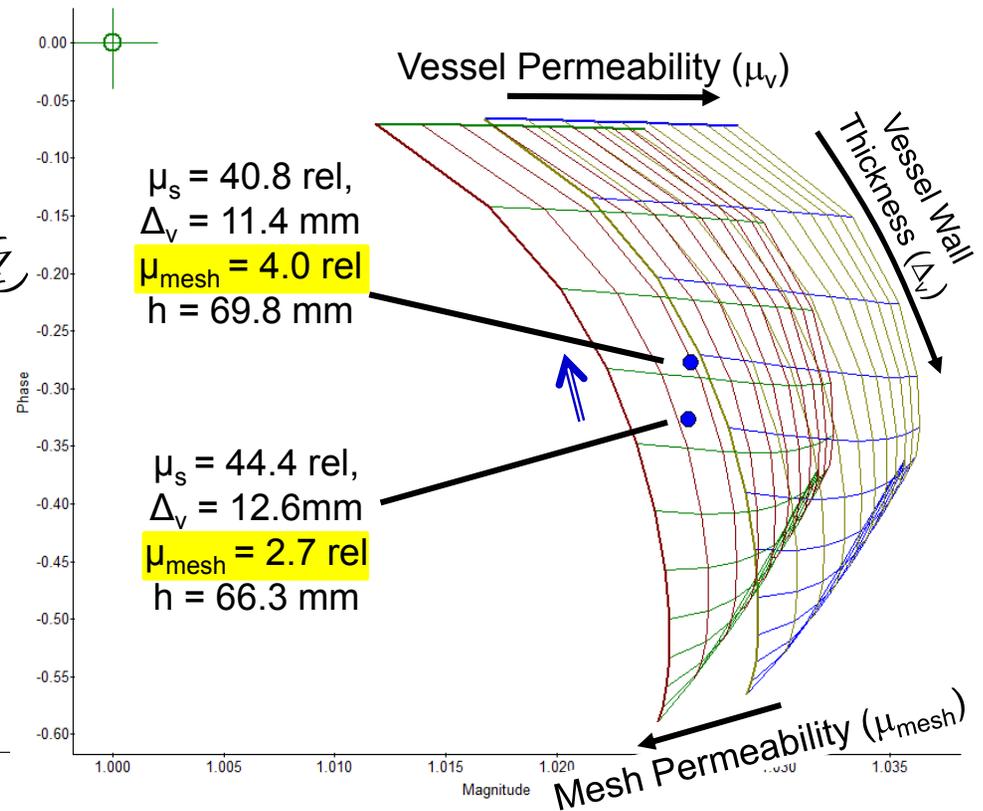


Sensitivity to Mesh Permeability and Concrete Thickness

Concrete Thickness Effect



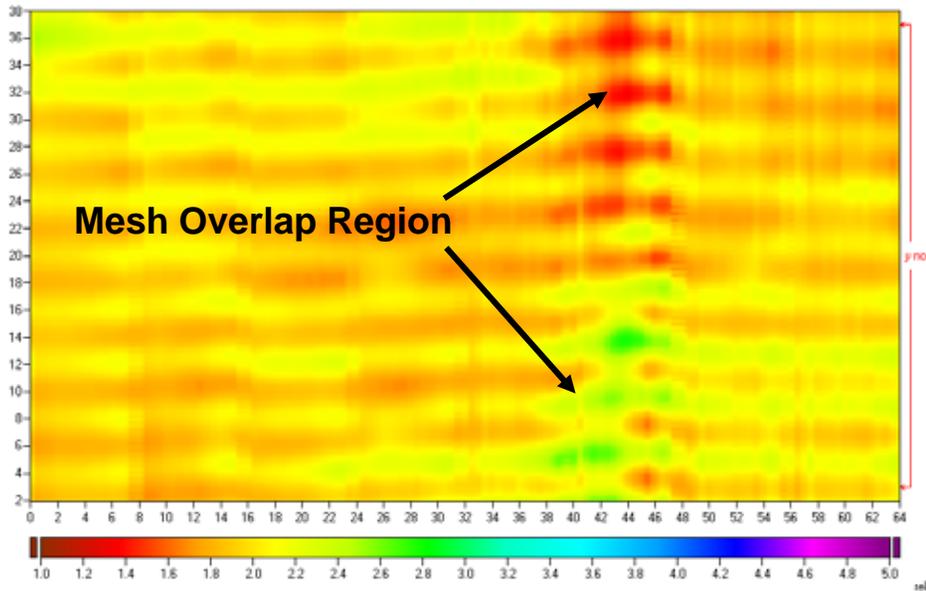
Wire Mesh “Effective” Permeability Effect



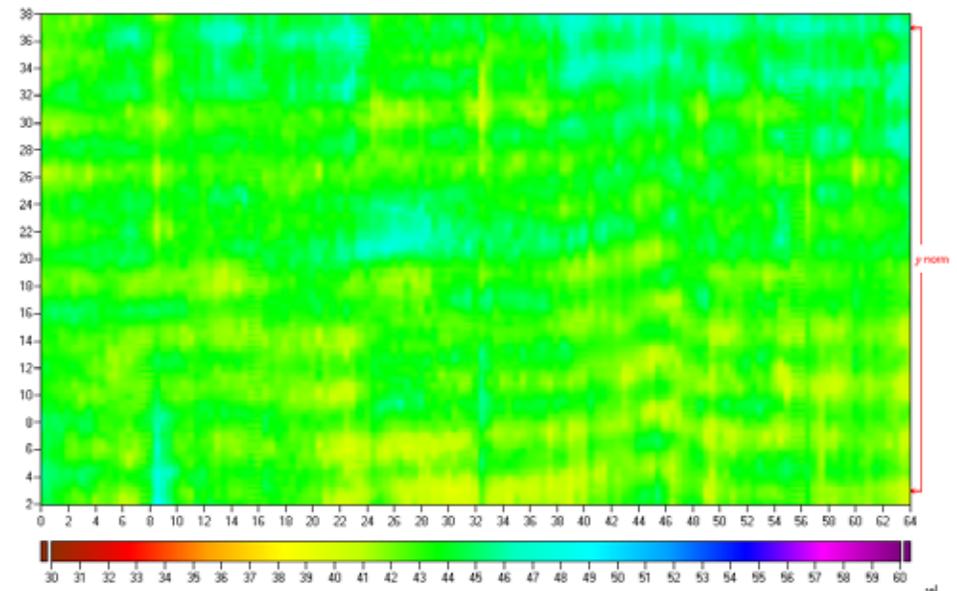
Note: This mesh effect is in the vessel wall thickness direction

Removing Mesh Contribution

Mesh Permeability

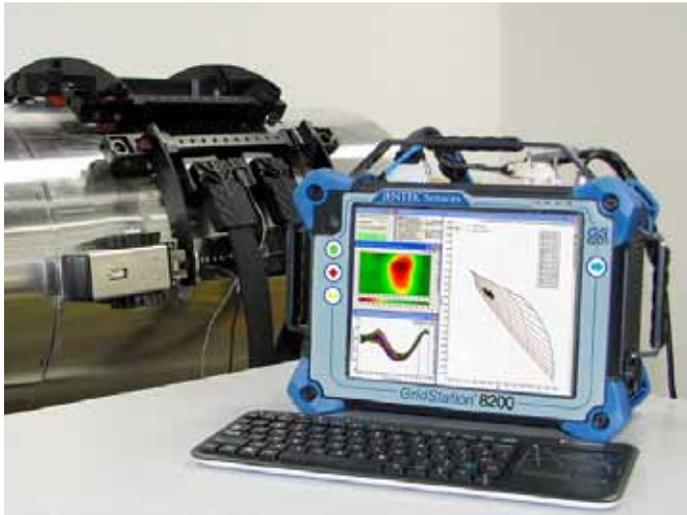


Wall Permeability



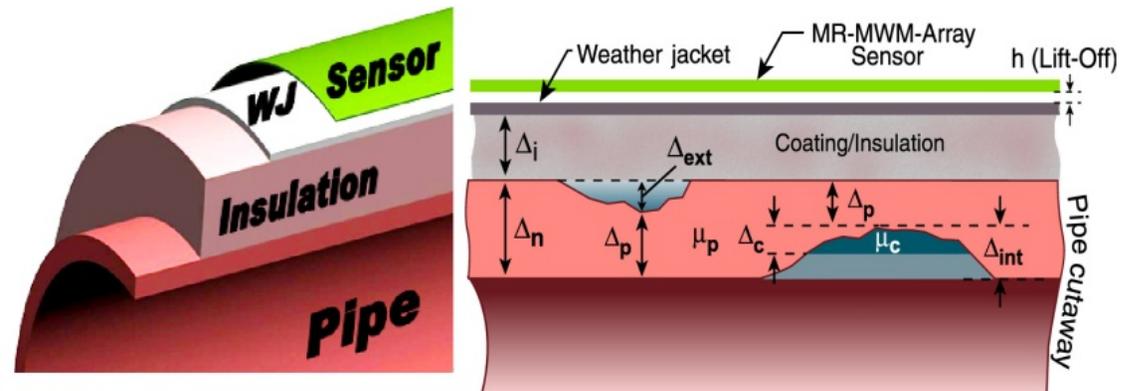
Mesh Models Still Under Development

MWM-Array Imaging of External and Internal Corrosion through Insulation with Weather Jacket



JENTEK Sensors Video

Problem Definition

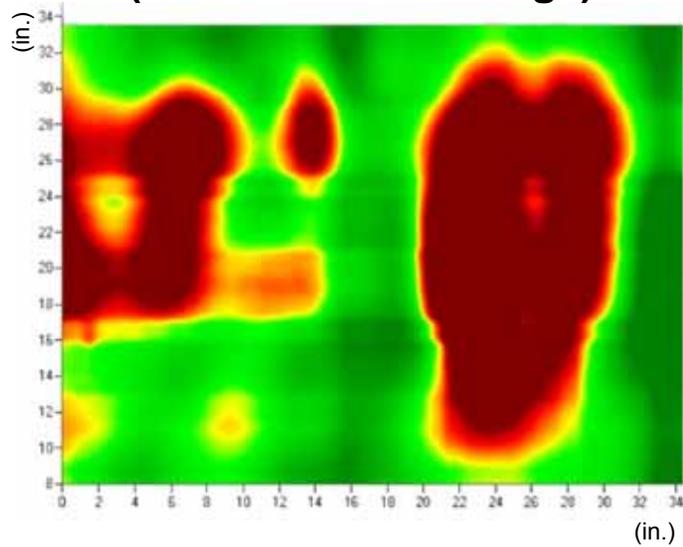


- Δ_p = Remaining pipe wall thickness
- μ_p = Pipe wall magnetic permeability
- Δ_{ext} = External wall loss
- Δ_{int} = Internal wall loss
- Δ_n = Nominal pipe wall thickness

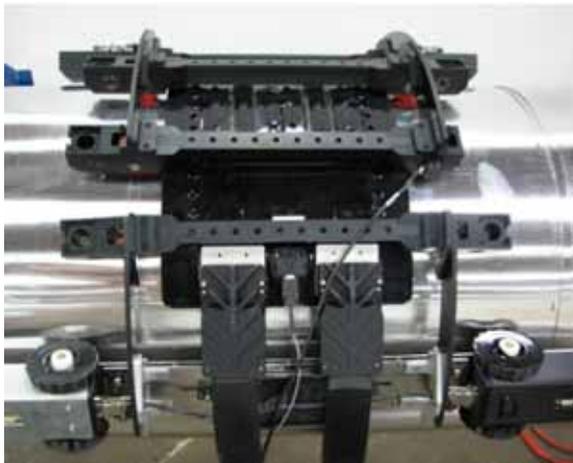
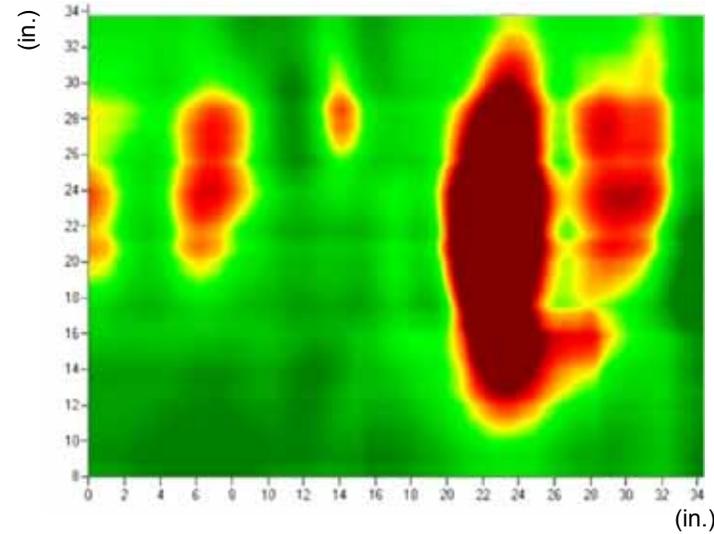
- h = Lift-off
- μ_c = Permeability of internal corrosion product layer
- Δ_c = Thickness of internal corrosion product layer
- Δ_i = Coating/insulation thickness

MWM-Array Inspection for CUI

**Pre-Alpha System Performance
(Wall Thickness Image)**



**Improved Resolution with Alpha System
(Wall Thickness Image)**



Summary

- **Demonstrated capability to:**
 - Correct for wire mesh
 - Image vessel skirt wall thickness
 - Scan large areas
- **Future work**
 - Improve scanner
 - Improve sensor effective footprint
 - Improve mesh model
 - Additional field trials in approvals

